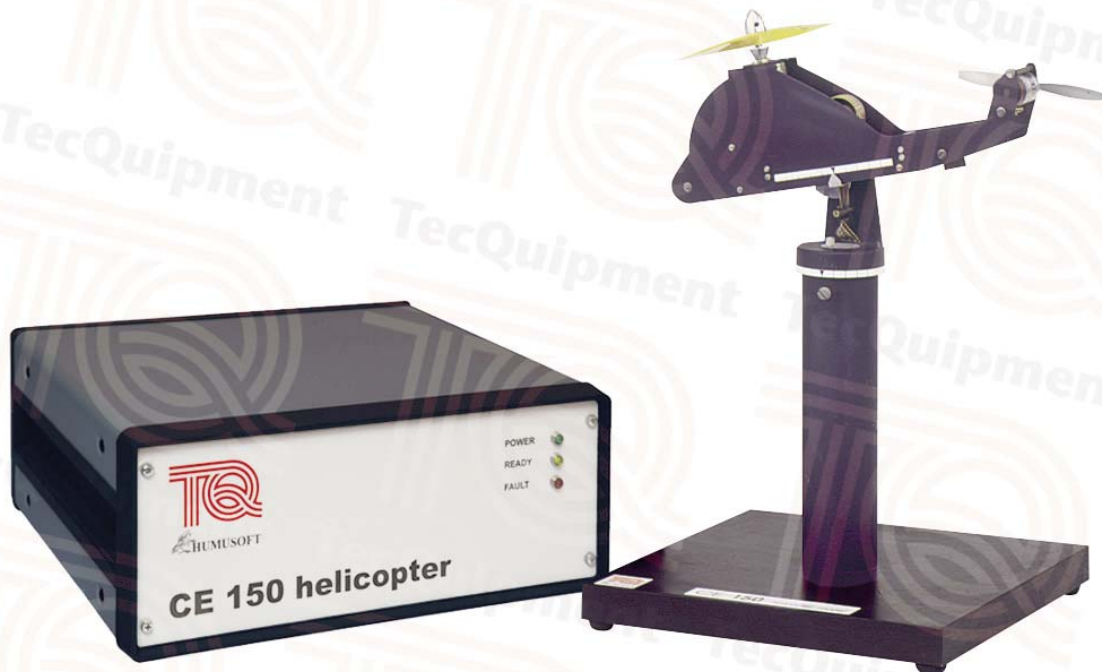




# CE150

## Helicopter Model

***Shows students how to create a controller to control a dynamic, naturally unstable system (a helicopter)***



- Compact, bench-top unit for connection to a suitable computer
- Real-time control of a multi-dimensional, naturally unstable system
- Two-input, two-output system with cross-coupling
- Scale-model of a helicopter with main (horizontal) rotor and tail rotor for realistic experience of yaw and pitch control
- Model has adjustable centre of gravity to mimic changes in weight distribution and to test the control system
- System accessible directly from MATLAB®/Simulink environment in real time
- Ideal for classroom demonstrations and student project work
- Includes comprehensive Educational Manual

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- An ISO 9001 certified company

# CE150

# Helicopter Model

## Description

The model simulates a helicopter with horizontal and tail rotors to give pitch and yaw control. Sensors measure the yaw and pitch angles. This gives a two-input and two output system, with cross-coupling. Students use the educational manual (supplied) to help identify plant dynamics and create a control system. The control system must keep the helicopter stable and allow for a change in the centre of gravity. When operating near the steady state, the electromechanical system can be linearized to a six-order model.

The equipment includes:

- The model helicopter on a stand
- An interface unit
- A data acquisition board for your computer
- A protective steel cage to put around the helicopter for safety

The Data Acquisition board fits into a suitable computer (not supplied) to link with the interface and control the motors of the helicopter, and accept inputs from the sensors.

The software (supplied) includes:

- Demonstration program with PID controllers
- Interface library for programming at the system level
- Example Simulink® models for real-time control experiments.

## Essential Ancillaries

(Not supplied by TecQuipment)

- Suitable computer with a spare PCIe (PCI Express) slot and Microsoft® Windows® XP, Vista, 7 or 8 operating system. 32-bit and 64-bit.

**Note:** If you have an older computer with only PCI slots, please contact our sales department.

- Software:
  - MATLAB®
  - Simulink
  - Real-Time Windows® Target
  - Simulink Coder® (recommended)
  - Simulink 3D Animation (recommended)

## Standard Features

- Supplied with comprehensive user guide and educational manual
- Five-year warranty
- Made in accordance with the latest European Union directives

## Experiments

- Direct derivation of a general mathematical model of a helicopter using Lagrange equations, linearisation and simplification.
- On-line identification of parameters of a linear model. Direct and indirect (closed-loop response analysis) methods should be used.
- System decoupling techniques, diagonalisation of system transfer matrix and state space methods.
- Stabilisation and tracking tasks formulation
- State feedback design, observer design
- Robust and adaptive controller design for changing parameters system due to moving centre of gravity, LQ/LQG and  $H_\infty$  controller design.
- Comparison of an analogue and digital controller design. Selection of a correct sampling frequency.

## Essential Services

*Electrical supply:*

220/240 VAC, 200 W, 50 Hz, with earth

*Bench space needed:*

1.5 m x 900 mm

## Operating Conditions

*Operating environment:*

Laboratory

*Storage temperature range:*

-25°C to +55°C (when packed for transport)

*Operating temperature range:*

+5°C to +40°C

*Operating relative humidity range:*

80% at temperatures < 31°C decreasing linearly to 50% at 40°C

## Sound Levels

Less than 70 dB(A)

## Specifications

*Helicopter Model Length:*

300 mm (without propellers), 370 mm (with propellers)

*Helicopter Model Height:* 440 mm

*Helicopter Model Support:* square base 300 x 300 mm

The model is protected by a rigid steel cage, 800 x 800 x 800 mm.

*Helicopter Nett weight:* 3.5 kg

*Interface unit:* 480 x 140 x 307 mm, 5.5 kg

*Data Acquisition Board:* PCIe x1

*Approximate packed dimensions and weight:*

0.15 m<sup>3</sup> and 15 kg

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